SIEMENS

Data sheet

6ES7510-1DJ01-0AB0



SIMATIC DP, CPU 1510SP-1 PN for ET 200SP, Central processing unit with Work memory 100 KB for program and 750 KB for data, 1st interface: PROFINET IRT with 3-port switch, 72 ns bit performance, SIMATIC Memory Card required, BusAdapter required for Port 1 and 2

General information	
Product type designation	CPU 1510SP-1 PN
HW functional status	FS05
Firmware version	V2.9
Product function	
• I&M data	Yes; I&M0 to I&M3
 Module swapping during operation (hot swapping) 	Yes; Multi-hot swapping
Isochronous mode	Yes; Only with PROFINET; with minimum OB 6x cycle of 625 µs
Engineering with	
 STEP 7 TIA Portal configurable/integrated from version 	V17 (FW V2.9) / V13 SP1 Update 4 (FW V1.8) or higher
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
 Mains/voltage failure stored energy time 	5 ms
Input current	
Current consumption (rated value)	0.6 A
Current consumption, max.	0.9 A
Inrush current, max.	4.7 A; Rated value
²t	0.14 A ² ·s
Power	
Infeed power to the backplane bus	8.75 W
Power loss	
Power loss, typ.	5.6 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
• integrated (for program)	100 kbyte
 integrated (for data) 	750 kbyte
Load memory	
 Plug-in (SIMATIC Memory Card), max. 	32 Gbyte

Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	72 ns
for word operations, typ.	86 ns
for fixed point arithmetic, typ.	115 ns
for floating point arithmetic, typ.	461 ns
CPU-blocks	
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	750 kbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	
Number range	0 65 535
• Size, max.	100 kbyte
FC	
Number range	0 65 535
• Size, max.	100 kbyte
OB	
• Size, max.	100 kbyte
 Number of free cycle OBs 	100
 Number of time alarm OBs 	20
 Number of delay alarm OBs 	20
 Number of cyclic interrupt OBs 	20; With minimum OB 3x cycle of 500 µs
 Number of process alarm OBs 	50
 Number of DPV1 alarm OBs 	3
 Number of isochronous mode OBs 	1
 Number of technology synchronous alarm OBs 	2
 Number of startup OBs 	100
 Number of asynchronous error OBs 	4
 Number of synchronous error OBs 	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
• Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
• Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	128 kbyte; Available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 88 KB
Flag	40.16.46
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	

Retentivity adjustable	Yes
Retentivity adjustable Retentivity preset	No
Retentivity preset Local data	
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	1.024: may number of modulos / submodulos
I/O address area	1 024; max. number of modules / submodules
Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	52 kbyte, All outputs are in the process image
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
 Number of subprocess images, max. 	32
Address space per module	
Address space per module, max.	288 byte; For input and output data respectively
Address space per station	
Address space per station, max.	2 560 byte; for central inputs and outputs; depending on configuration; 2
· ·	048 bytes for ET 200SP modules + 512 bytes for ET 200AL modules
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
Via CM	1
Number of IO Controllers	
integrated	1
• Via CM	0
Rack	
Modules per rack, max.	80; CPU + 64 modules + server module (mounting width max. 1 m) + 16 ET 200AL modules
 Quantity of operable ET 200SP modules, max. 	64
 Quantity of operable ET 200AL modules, max. 	16
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Туре	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Тур.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
• supported	Yes
• to DP, master	Yes; Via CM DP module
• to DP, slave	Yes; Via CM DP module
• in AS, master	Yes
• in AS, slave	Yes
on Ethernet via NTP	Yes
Interfaces	
Number of PROFINET interfaces	
Number of PROFIBUS interfaces	1; Via CM DP module
Optical interface	No
1. Interface	
Interface types	

• RJ 45 (Ethernet)	Yes; X1 P3; opt. X1 P1 and X1 P2 via BusAdapter BA 2x RJ45
Number of ports	3; 1. integr. + 2. via BusAdapter
integrated switch	Yes
BusAdapter (PROFINET)	Yes; compatible BusAdapters: BA 2x RJ45, BA 2x FC, BA 2x M12
Protocols IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— Isochronous mode	Yes
— Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	64; In total, up to 256 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
 — Of which IO devices with IRT, max. 	64
 Number of connectable IO Devices for RT, max. 	64
— of which in line, max.	64
- Number of IO Devices that can be	8; in total across all interfaces
simultaneously activated/deactivated, max.	
 — Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 250 μs	250 μs to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625 μs of the isochronous OB is decisive
— for send cycle of 500 μs	500 μs to 8 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625 μs of the isochronous OB is decisive
— for send cycle of 1 ms	1 ms to 16 ms
 for send cycle of 2 ms 	2 ms to 32 ms
 for send cycle of 4 ms 	4 ms to 64 ms
 With IRT and parameterization of "odd" send cycles 	Update time = set "odd" send clock (any multiple of 125 μs : 375 μs , 625 μs 3 875 $\mu s)$
Update time for RT	
— for send cycle of 250 μs	250 µs to 128 ms
— for send cycle of 500 μs	500 µs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
 for send cycle of 2 ms 	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	Vee
— PG/OP communication	Yes
— Isochronous mode	No
	Yes
— PROFlenergy	Yes; per user program
— Shared device Number of IQ Controllers with shared device	Yes
 Number of IO Controllers with shared device, 	4
max.	
- activation/deactivation of I-devices	Yes; per user program
 — activation/deactivation of I-devices — Asset management record 	Yes; per user program Yes; per user program
 — activation/deactivation of I-devices — Asset management record 2. Interface 	
 — activation/deactivation of I-devices — Asset management record 	

Number of ports	1
Number of ports	1
Protocols	Mar.
PROFIBUS DP master	Yes
PROFIBUS DP slave	Yes
SIMATIC communication	Yes
PROFIBUS DP master	
Number of connections, max.	48; Of which 4 each reserved for ES and HMI
 Number of DP slaves, max. 	125; In total, up to 256 distributed I/O devices can be connected via AS-
Comisso	i, PROFIBUS or PROFINET
Services	Mar.
— PG/OP communication	Yes
— Equidistance	No
— Isochronous mode	No
— Activation/deactivation of DP slaves	Yes
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
 Autonegotiation 	Yes
Autocrossing	Yes
 Industrial Ethernet status LED 	Yes
RS 485	
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	No
Number of connections	
 Number of connections, max. 	96; via integrated interfaces of the CPU and connected CPs / CMs
Number of connections reserved for ES/HMI/web	10
Number of connections via integrated interfaces	64
Number of connections per CP/CM	32
Number of S7 routing paths	16
	10
Redundancy mode	
Redundancy mode	Voc
H-Sync forwarding	Yes
H-Sync forwarding Media redundancy	
 H-Sync forwarding Media redundancy — Media redundancy 	Yes; only via BusAdapter
H-Sync forwarding Media redundancy	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP
 H-Sync forwarding Media redundancy — Media redundancy — MRP 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
 H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
 H-Sync forwarding Media redundancy Media redundancy MRP MRP interconnection, supported MRPD 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT
 H-Sync forwarding Media redundancy Media redundancy MRP MRP interconnection, supported MRPD Switchover time on line break, typ. 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD
 H-Sync forwarding Media redundancy Media redundancy MRP MRP interconnection, supported MRPD Switchover time on line break, typ. Number of stations in the ring, max. 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT
 H-Sync forwarding Media redundancy Media redundancy MRP MRP interconnection, supported MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50
H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP — MRP interconnection, supported — MRPD — Switchover time on line break, typ. — Number of stations in the ring, max. SIMATIC communication • PG/OP communication	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected
 H-Sync forwarding Media redundancy Media redundancy MRP MRP MRP interconnection, supported MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes
 H-Sync forwarding Media redundancy Media redundancy MRP MRP MRP interconnection, supported MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication PG/OP communication \$7 routing Data record routing 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes
 H-Sync forwarding Media redundancy Media redundancy MRP MRP MRP interconnection, supported MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing Data record routing S7 communication, as server 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes Yes
 H-Sync forwarding Media redundancy Media redundancy MRP MRP MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing Data record routing S7 communication, as server S7 communication, as client 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes Yes Yes
 H-Sync forwarding Media redundancy Media redundancy MRP MRP MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing Data record routing S7 communication, as server S7 communication, as client User data per job, max. 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes Yes
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 H-Sync forwarding Media redundancy Media redundancy MRP MRP interconnection, supported MRPD Switchover time on line break, typ. Number of stations in the ring, max. SIMATIC communication PG/OP communication \$7 routing Data record routing \$7 communication, as server \$7 communication, as client User data per job, max. Open IE communication TCP/IP Data length, max. supported ISO-on-TCP (RFC1006) Data length, max. UDP Data length, max. UDP multicast DHCP 	Yes; only via BusAdapter Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes Yes Yes See online help (S7 communication, user data size) Yes 64 kbyte Yes 94 kbyte Yes 2 kbyte; 1 472 bytes for UDP broadcast Yes; Max. 5 multicast circuits Yes
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• LLDP	Yes
ELDI Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes
- Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
 — User authentication 	"anonymous" or by user name & password
 — Number of connections, max. 	4
 Number of nodes of the client interfaces, max. 	1 000
 — Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/C max. 	300
 — Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20
 — Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100
 — Number of simultaneous calls of the client instructions per connection (except OPC_UA_ReadList,OPC_UA_WriteList,OPC_UA_M max. 	1
 — Number of simultaneous calls of the client instructions OPC_UA_ReadList,OPC_UA_WriteList and OPC_UA_MethodCall, max. 	5
— Number of registerable nodes, max.	5 000
 Number of registerable method calls of OPC_UA_MethodCall, max. 	100
 — Number of inputs/outputs when calling OPC_UA_MethodCall, max. 	20
OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address space
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
 — GDS support (certificate management) 	Yes
— Number of sessions, max.	32
- Number of accessible variables, max.	50 000
 Number of registerable nodes, max. 	10 000
— Number of subscriptions per session, max.	20
— Sampling interval, min.	100 ms
 — Publishing interval, min. — Number of server methods, max. 	500 ms 20
 Number of server methods, max. Number of inputs/outputs per server method, max. 	20
 Number of monitored items, max. 	1 000; for 1 s sampling interval and 1 s send interval
— Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
 — Number of nodes for user-defined server interfaces, max. 	1 000
Alarms and Conditions	Yes
— Number of program alarms	100
 — Number of alarms for system diagnostics 	50
Further protocols	
• MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32
Program alarms	Yes
Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm"

	block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	2 500
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	0
Status/control variable	Yes
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
Number of variables, max.	inputs/outputs, memory bits, DDs, distributed i/Os, timers, counters
of which status variables, max.	200: por job
— of which control variables, max.	200; per job
Forcing	200; per job
Forcing	Yes
-	
 Forcing, variables Number of variables, max. 	Peripheral inputs/outputs 200
	200
Diagnostic buffer	Vaa
present	Yes
Number of entries, max. of which poworfail proof	1 000
— of which powerfail-proof	500
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
 Monitoring of the supply voltage (PWR-LED) 	Yes
Connection display LINK TX/RX	Yes
Supported technology objects	
Supported technology objects Motion Control	Yes; Note: The number of technology objects affects the cycle time of
Motion Control	the PLC program; selection guide via the TIA Selection Tool
Motion Control Number of available Motion Control resources for 	
Motion Control Number of available Motion Control resources for technology objects 	the PLC program; selection guide via the TIA Selection Tool
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources 	the PLC program; selection guide via the TIA Selection Tool 800
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis 	the PLC program; selection guide via the TIA Selection Tool 800 40
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis 	the PLC program; selection guide via the TIA Selection Tool 800 40 80
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160
 Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder 	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80
 Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam 	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160
 Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) 	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5
 Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control 	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5
 Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) 	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5
Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per output cam — per probe • Positioning axis — per probe • Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10
Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per output cam — per probe • Positioning axis — per probe • Positioning axis — per probe • Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization
Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per output cam — per probe • Positioning axis — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_3Step	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per output cam — per probe • Positioning axis — per probe • Positioning axis — per probe • Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_Temp	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per output cam — per probe • Positioning axis — per probe • Positioning axis — per probe • Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_Temp Counting and measuring	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for valves
Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per output cam — per output cam — per probe • Positioning axis — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID-Temp Counting and measuring • High-speed counter	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for valves
Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_Temp Counting and measuring • High-speed counter Ambient conditions	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes
Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe • Positioning axis — number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID-Temp Counting and measuring • High-speed counter Ambient temperature during operation • horizontal installation, min.	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for valves
Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe • Positioning axis — number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID-Temp Counting and measuring • High-speed counter Ambient temperature during operation • horizontal installation, min. • horizontal installation, max.	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes
Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe • Positioning axis — number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID-Temp Counting and measuring • High-speed counter Ambient temperature during operation • horizontal installation, min.	the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes PID controller with integrated optimization for temperature

Altitude during operation relating to sea level	
 Installation altitude above sea level, max. 	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— GRAPH	Yes
Know-how protection	
 User program protection/password protection 	Yes
Copy protection	Yes
Block protection	Yes
Access protection	
 protection of confidential configuration data 	Yes
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
 Protection level: Complete protection 	Yes
programming / cycle time monitoring / header	
lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	100 mm
Height	117 mm
Depth	75 mm
Veights	
Weight, approx.	310 g
last modified:	11/3/2021 🖸