## **SIEMENS**

## **Data sheet**

6ES7212-1AE40-0XB0



Figure similar

SIMATIC S7-1200, CPU 1212C, compact CPU, DC/DC/DC, onboard I/O: 8 DI 24 V DC; 6 DO 24 V DC; 2 AI 0-10 V DC, Power supply: DC 20.4-28.8V DC, Program/data memory 75 KB

General information	
Product type designation	CPU 1212C DC/DC/DC
Firmware version	V4.5
Engineering with	
<ul> <li>Programming package</li> </ul>	STEP 7 V17 or higher
Supply voltage	
Rated value (DC)	
• 24 V DC	Yes
permissible range, lower limit (DC)	20.4 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Load voltage L+	
<ul><li>Rated value (DC)</li></ul>	24 V
<ul> <li>permissible range, lower limit (DC)</li> </ul>	20.4 V
<ul> <li>permissible range, upper limit (DC)</li> </ul>	28.8 V
Input current	
Current consumption (rated value)	400 mA; CPU only
Current consumption, max.	1 200 mA; CPU with all expansion modules
Inrush current, max.	12 A; at 28.8 V DC
l²t	0.5 A <sup>2</sup> ·s
Output current	
for backplane bus (5 V DC), max.	1 000 mA; Max. 5 V DC for SM and CM
Encoder supply	
24 V encoder supply	
• 24 V	L+ minus 4 V DC min.
Power loss	
Power loss, typ.	9 W
Memory	
Work memory	
• integrated	75 kbyte
• expandable	No
Load memory	
• integrated	2 Mbyte
Plug-in (SIMATIC Memory Card), max.	with SIMATIC memory card
Backup	
<ul><li>present</li></ul>	Yes
<ul> <li>maintenance-free</li> </ul>	Yes
without battery	Yes

CPU processing times	
for bit operations, typ.	0.08 µs; / instruction
for word operations, typ.	1.7 μs; / instruction
for floating point arithmetic, typ.	2.3 µs; / instruction
CPU-blocks	2.0 μ0; / πιοτισσιοτί
Number of blocks (total)	DBs, FCs, FBs, counters and timers. The maximum number of addressable blocks ranges from 1 to 65535. There is no restriction, the entire working memory can be used
OB	
<ul><li>Number, max.</li></ul>	Limited only by RAM for code
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	14 kbyte
Flag	
• Size, max.	4 kbyte; Size of bit memory address area
Local data	
• per priority class, max.	16 kbyte; Priority class 1 (program cycle): 16 KB, priority class 2 to 26: 6 KB
Address area	
Process image	
Inputs, adjustable	1 kbyte
Outputs, adjustable	1 kbyte
Hardware configuration	
Number of modules per system, max.	3 comm. modules, 1 signal board, 2 signal modules
Time of day	o commitmentation, i digital boatia, <u>a</u> digital moduloc
Clock	
Hardware clock (real-time)	Yes
• • •	
Backup time     Deviation per day, may	480 h; Typical
Deviation per day, max.  District in parts.	±60 s/month at 25 °C
Digital inputs	
Number of digital inputs	8; Integrated
of which inputs usable for technological functions	6; HSC (High Speed Counting)
Source/sink input	Yes
Number of simultaneously controllable inputs	
all mounting positions	0
— up to 40 °C, max.	8
Input voltage	2414
Rated value (DC)	24 V
• for signal "0"	5 V DC at 1 mA
• for signal "1"	15 V DC at 2.5 mA
Input delay (for rated value of input voltage)	
for standard inputs	00
— parameterizable	0.2 ms, 0.4 ms, 0.8 ms, 1.6 ms, 3.2 ms, 6.4 ms and 12.8 ms, selectable in groups of four 0.2 ms
— at "0" to "1", min.	
— at "0" to "1", max.	12.8 ms
for interrupt inputs  — parameterizable	Yes
·	165
for technological functions  — parameterizable	Single phase: 3 @ 100 kHz 2 2 @ 20 kHz differential: 2 @ 00 kHz 2 2
·	Single phase: 3 @ 100 kHz & 3 @ 30 kHz, differential: 3 @ 80 kHz & 3 @ 30 kHz
Cable length	500 m; 50 m for technological functions
shielded, max.      unabiolded, max.	500 m; 50 m for technological functions
• unshielded, max.	300 m; for technological functions: No
Digital outputs	
Number of digital outputs	6
of which high-speed outputs	4; 100 kHz Pulse Train Output
Limitation of inductive shutdown voltage to	L+ (-48 V)
Switching capacity of the outputs	
with resistive load, max.      on lamp load, max.	0.5 A 5 W

Output voltage	0.477 (#.4010)
• for signal "0", max.	0.1 V; with 10 kOhm load
• for signal "1", min.	20 V
Output current	
<ul><li>for signal "1" rated value</li></ul>	0.5 A
for signal "0" residual current, max.	0.1 mA
Output delay with resistive load	
• "0" to "1", max.	1 µs
• "1" to "0", max.	5 μs
Switching frequency	
of the pulse outputs, with resistive load, max.	100 kHz
Relay outputs	
Number of relay outputs	0
Cable length	
<ul><li>shielded, max.</li></ul>	500 m
<ul><li>unshielded, max.</li></ul>	150 m
Analog inputs	
Number of analog inputs	2
Input ranges	
• Voltage	Yes
Input ranges (rated values), voltages	
• 0 to +10 V	Yes
— Input resistance (0 to 10 V)	≥100k ohms
Cable length	
shielded, max.	100 m; twisted and shielded
Analog outputs	Too III, twisted and officiaed
	0
Number of analog outputs	0
Analog value generation for the inputs	
Integration and conversion time/resolution per channel	
<ul> <li>Resolution with overrange (bit including sign), max.</li> </ul>	10 bit
<ul> <li>Integration time, parameterizable</li> </ul>	Yes
<ul><li>Integration time, parameterizable</li><li>Conversion time (per channel)</li></ul>	Yes 625 μs
Conversion time (per channel)	
Conversion time (per channel)     Encoder	
Conversion time (per channel)  Encoder  Connectable encoders	625 μs
Conversion time (per channel)  Encoder  Connectable encoders      2-wire sensor  1. Interface	625 μs
Conversion time (per channel)  Encoder  Connectable encoders      2-wire sensor	625 μs Yes
<ul> <li>Conversion time (per channel)</li> <li>Encoder</li> <li>Connectable encoders</li> <li>2-wire sensor</li> <li>Interface</li> <li>Interface type</li> </ul>	625 μs  Yes  PROFINET
Conversion time (per channel)  Encoder  Connectable encoders     2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate	Yes  PROFINET Yes
Conversion time (per channel)  Encoder  Connectable encoders     2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation	PROFINET Yes Yes
Conversion time (per channel)  Encoder  Connectable encoders     2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation Autocrossing	Yes  PROFINET  Yes  Yes  Yes  Yes
Conversion time (per channel)  Encoder  Connectable encoders     2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation  Autocrossing Interface types	Yes  PROFINET  Yes  Yes  Yes  Yes
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation  Autocrossing Interface types  RJ 45 (Ethernet)	Yes  PROFINET  Yes  Yes  Yes  Yes  Yes  Yes
Conversion time (per channel)  Encoder  Connectable encoders     2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation  Autocrossing Interface types     RJ 45 (Ethernet)     Number of ports	Yes  PROFINET  Yes  Yes  Yes  Yes  Yes  Yes  Yes  Ye
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch	Yes  PROFINET  Yes  Yes  Yes  Yes  Yes  Yes
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate  Autonegotiation  Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols	Yes  PROFINET Yes Yes Yes Yes Yes 1 No
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller	Yes  PROFINET Yes Yes Yes Yes Yes You Yes Yes 1 No
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation  Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device	Yes  PROFINET  Yes  Yes  Yes  Yes  Yes  Yes  Yes  Ye
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate  Autonegotiation  Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device  SIMATIC communication	Yes  PROFINET  Yes  Yes  Yes  Yes  Yes  Yes  Yes  Ye
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate  Autonegotiation  Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device  SIMATIC communication  Open IE communication	Yes  PROFINET Yes Yes Yes Yes Yes Yes Yes Yes 1 No  Yes Yes Yes Yes Yes Yes Yes Yes Yes Ye
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate  Autonegotiation Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device  SIMATIC communication  Open IE communication  Web server	Yes  PROFINET Yes Yes Yes Yes Yes Yes Yes  Yes 1 No  Yes Yes Yes Yes Yes Yes Yes Yes Yes Ye
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device  SIMATIC communication  Open IE communication  Web server  Media redundancy	Yes  PROFINET Yes Yes Yes Yes Yes Yes Yes Yes 1 No  Yes Yes Yes Yes Yes Yes Yes Yes Yes Ye
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation  Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device  SIMATIC communication  Open IE communication  Web server  Media redundancy  PROFINET IO Controller	Yes  PROFINET Yes Yes Yes Yes Yes Yes Yes Yes Optionally also encrypted Yes No
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate  Autonegotiation Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device  SIMATIC communication  Open IE communication  Web server  Media redundancy  PROFINET IO Controller  PROFINET IO Controller  Transmission rate, max.	Yes  PROFINET Yes Yes Yes Yes Yes Yes Yes  Yes 1 No  Yes Yes Yes Yes Yes Yes Yes Yes Yes Ye
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate  Autonegotiation Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device  SIMATIC communication  Open IE communication  Web server  Media redundancy  PROFINET IO Controller  Transmission rate, max.  Services	Yes  PROFINET Yes Yes Yes Yes Yes Yes Yes On the state of
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device  SIMATIC communication  Open IE communication  Web server  Media redundancy  PROFINET IO Controller  Transmission rate, max.  Services  — PG/OP communication	Yes  PROFINET Yes Yes Yes Yes Yes Yes  Yes  1 No  Yes Yes Yes Yes Yes Yes Yes Yes Yes Ye
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate  Autonegotiation Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device  SIMATIC communication  Open IE communication  Web server  Media redundancy  PROFINET IO Controller  Transmission rate, max.  Services  — PG/OP communication  — Isochronous mode	Yes  PROFINET Yes Yes Yes Yes Yes Yes Yes  1 No  Yes Yes Yes Yes Yes Yes Yes Yes Yes Ye
Conversion time (per channel)  Encoder  Connectable encoders  2-wire sensor  1. Interface Interface type Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types  RJ 45 (Ethernet)  Number of ports  integrated switch  Protocols  PROFINET IO Controller  PROFINET IO Device  SIMATIC communication  Open IE communication  Web server  Media redundancy  PROFINET IO Controller  Transmission rate, max.  Services  — PG/OP communication	Yes  PROFINET Yes Yes Yes Yes Yes Yes  Yes  1 No  Yes Yes Yes Yes Yes Yes Yes Yes Yes Ye

B. W	V
— Prioritized startup	Yes
<ul> <li>Number of IO devices with prioritized startup,</li> </ul>	16
max.	40
Number of connectable IO Devices, max.	16
<ul> <li>Number of connectable IO Devices for RT, max.</li> </ul>	16
— of which in line, max.	16
<ul> <li>Activation/deactivation of IO Devices</li> </ul>	Yes
<ul> <li>Number of IO Devices that can be</li> </ul>	8
simultaneously activated/deactivated, max.	
— Updating time	The minimum value of the update time also depends on the communication component set for PROFINET IO, on the number of IO devices and the quantity of configured user data.
PROFINET IO Device	
Services	
— PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
— Isochronous mode	No
— IRT	No
— PROFlenergy	Yes
— PROFileHeigy      — Shared device	Yes
<ul> <li>Number of IO Controllers with shared device, max.</li> </ul>	2
Protocols	
	Yes
Supports protocol for PROFINET IO	
PROFINIO	No
PROFIBUS	Yes; CM 1243-5 (master) or CM 1242-5 (slave) required
OPC UA	Yes; OPC UA Server
AS-Interface	Yes; CM 1243-2 required
Protocols (Ethernet)	
• TCP/IP	Yes
• DHCP	No
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Redundancy mode	
Media redundancy	
— MRP	No
— MRPD	No
SIMATIC communication	
S7 routing	Yes
Open IE communication	
• TCP/IP	Yes
— Data length, max.	8 kbyte
several passive connections per port,	Yes
supported	
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	8 kbyte
• UDP	Yes
— Data length, max.	1 472 byte
Web server	
supported	Yes
User-defined websites	Yes
OPC UA	
Runtime license required	Yes; "Basic" license required
OPC UA Server	Yes; data access (read, write, subscribe), method call, runtime license
• OI O OA GEIVEI	required
<ul> <li>Application authentication</li> </ul>	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
<ul> <li>User authentication</li> </ul>	"anonymous" or by user name & password
Number of sessions, max.	10
Number of subscriptions per session, max.	50
— Sampling interval, min.	100 ms
- Camping interval, film.	

<ul><li>— Publishing interval, min.</li></ul>	200 ms
<ul> <li>Number of server methods, max.</li> </ul>	20
<ul> <li>Number of monitored items, max.</li> </ul>	1 000
<ul> <li>Number of server interfaces, max.</li> </ul>	2
<ul> <li>Number of nodes for user-defined server</li> </ul>	2 000
interfaces, max.	
Further protocols	
• MODBUS	Yes
communication functions / header	
S7 communication	
<ul><li>supported</li></ul>	Yes
• as server	Yes
• as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Number of connections	
• overall	PG Connections: 4 reserved / 4 max; HMI Connections: 12 reserved / 18 max; S7 Connections: 8 reserved / 14 max; Open User Connections: 8 reserved / 14 max; Web Connections: 2 reserved / 30 max; OPC UA Connections: 0 reserved / 10 max; Total Connections: 34 reserved / 64 max
Test commissioning functions	
Status/control	
Status/control variable	Yes
<ul> <li>Variables</li> </ul>	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
Forcing	
Forcing	Yes
Diagnostic buffer	
• present	Yes
Traces	
Number of configurable Traces	2
<ul> <li>Memory size per trace, max.</li> </ul>	512 kbyte
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
9	Yes Yes
RUN/STOP LED	
<ul><li>RUN/STOP LED</li><li>ERROR LED</li><li>MAINT LED</li></ul>	Yes
RUN/STOP LED  ERROR LED  MAINT LED  Integrated Functions	Yes
RUN/STOP LED     ERROR LED     MAINT LED  Integrated Functions  Counter	Yes Yes
RUN/STOP LED  ERROR LED  MAINT LED  Integrated Functions  Counter  Number of counters	Yes Yes
RUN/STOP LED ERROR LED MAINT LED Integrated Functions  Counter Number of counters Counting frequency, max.	Yes Yes
RUN/STOP LED ERROR LED MAINT LED Integrated Functions Counter Number of counters Counting frequency, max. Frequency measurement	Yes Yes  6 100 kHz Yes
RUN/STOP LED  ERROR LED  MAINT LED  Integrated Functions  Counter  Number of counters  Counting frequency, max.  Frequency measurement  controlled positioning	Yes Yes  6 100 kHz Yes Yes
RUN/STOP LED  ERROR LED  MAINT LED  Integrated Functions  Counter  Number of counters  Counting frequency, max.  Frequency measurement  controlled positioning  Number of position-controlled positioning axes, max.	Yes Yes  6 100 kHz Yes Yes Yes 8
RUN/STOP LED  ERROR LED  MAINT LED  Integrated Functions  Counter  Number of counters  Counting frequency, max.  Frequency measurement  controlled positioning	Yes Yes  6 100 kHz Yes Yes Yes 4; With integrated outputs
RUN/STOP LED ERROR LED MAINT LED Integrated Functions  Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller	Yes Yes  6 100 kHz Yes Yes Yes 8
RUN/STOP LED ERROR LED MAINT LED Integrated Functions Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs	Yes Yes  6 100 kHz Yes Yes Yes 4; With integrated outputs Yes
RUN/STOP LED ERROR LED MAINT LED  Integrated Functions  Counter Number of counters Counting frequency, max.  Frequency measurement controlled positioning  Number of position-controlled positioning axes, max.  Number of positioning axes via pulse-direction interface PID controller  Number of alarm inputs  Number of pulse outputs	Yes Yes  6 100 kHz Yes Yes Yes 4 4
RUN/STOP LED ERROR LED MAINT LED  Integrated Functions  Counter Number of counters Counting frequency, max.  Frequency measurement controlled positioning Number of position-controlled positioning axes, max.  Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs  Number of pulse outputs Limit frequency (pulse)	Yes Yes  6 100 kHz Yes Yes Yes 4; With integrated outputs Yes 4
RUN/STOP LED ERROR LED MAINT LED  Integrated Functions  Counter Number of counters Counting frequency, max.  Frequency measurement controlled positioning Number of position-controlled positioning axes, max.  Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse)  Potential separation	Yes Yes  6 100 kHz Yes Yes Yes 4 4
RUN/STOP LED ERROR LED MAINT LED Integrated Functions  Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse)  Potential separation Potential separation digital inputs	Yes Yes  6 100 kHz Yes Yes Yes 4 4 100 kHz
RUN/STOP LED ERROR LED MAINT LED Integrated Functions Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs Potential separation digital inputs	Yes Yes  6 100 kHz Yes Yes Yes 4 4 100 kHz
RUN/STOP LED ERROR LED MAINT LED Integrated Functions  Counter Number of counters Counting frequency, max.  Frequency measurement controlled positioning Number of position-controlled positioning axes, max.  Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse)  Potential separation  Potential separation digital inputs Potential separation digital inputs between the channels, in groups of	Yes Yes  6 100 kHz Yes Yes Yes 4 4 100 kHz
RUN/STOP LED ERROR LED MAINT LED  Integrated Functions  Counter Number of counters Counting frequency, max.  Frequency measurement controlled positioning Number of position-controlled positioning axes, max.  Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse)  Potential separation  Potential separation digital inputs Potential separation digital inputs between the channels, in groups of	Yes Yes  6 100 kHz Yes Yes Yes 8 4; With integrated outputs Yes 4 4 100 kHz  No 1
RUN/STOP LED ERROR LED MAINT LED  Integrated Functions  Counter Number of counters Counting frequency, max.  Frequency measurement controlled positioning Number of position-controlled positioning axes, max.  Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse)  Potential separation  Potential separation digital inputs  Potential separation digital inputs between the channels, in groups of  Potential separation digital outputs Potential separation digital outputs Potential separation digital outputs Potential separation digital outputs	Yes Yes  6 100 kHz Yes Yes Yes 8 4; With integrated outputs Yes 4 4 100 kHz  No 1
RUN/STOP LED ERROR LED MAINT LED Integrated Functions  Counter Number of counters Counting frequency, max. Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse)  Potential separation Potential separation digital inputs Potential separation digital inputs between the channels, in groups of Potential separation digital outputs	Yes Yes  6 100 kHz Yes Yes Yes 8 4; With integrated outputs Yes 4 4 100 kHz  No 1  Yes No
RUN/STOP LED ERROR LED MAINT LED  Integrated Functions  Counter Number of counters Counting frequency, max.  Frequency measurement controlled positioning  Number of position-controlled positioning axes, max.  Number of positioning axes via pulse-direction interface  PID controller  Number of alarm inputs  Number of pulse outputs  Limit frequency (pulse)  Potential separation  Potential separation digital inputs  Potential separation digital inputs  Potential separation digital outputs	Yes Yes  6 100 kHz Yes Yes Yes 8 4; With integrated outputs Yes 4 4 100 kHz  No 1
RUN/STOP LED ERROR LED MAINT LED  Integrated Functions  Counter Number of counters Counting frequency, max.  Frequency measurement controlled positioning Number of position-controlled positioning axes, max.  Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse)  Potential separation  Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs	Yes Yes  6 100 kHz Yes Yes Yes 8 4; With integrated outputs Yes 4 4 100 kHz  No 1  Yes No
RUN/STOP LED ERROR LED MAINT LED  Integrated Functions  Counter Number of counters Counting frequency, max.  Frequency measurement controlled positioning  Number of position-controlled positioning axes, max.  Number of positioning axes via pulse-direction interface PID controller  Number of alarm inputs  Number of pulse outputs  Limit frequency (pulse)  Potential separation  Potential separation digital inputs Potential separation digital inputs between the channels, in groups of  Potential separation digital outputs between the channels	Yes Yes  6 100 kHz Yes Yes Yes 8 4; With integrated outputs Yes 4 100 kHz  No 1  Yes No 1
RUN/STOP LED ERROR LED MAINT LED  Integrated Functions  Counter Number of counters Counting frequency, max.  Frequency measurement controlled positioning Number of position-controlled positioning axes, max.  Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse)  Potential separation  Potential separation digital inputs Potential separation digital inputs Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs  Potential separation digital outputs	Yes Yes  6 100 kHz Yes Yes Yes 8 4; With integrated outputs Yes 4 4 100 kHz  No 1  Yes No

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Test voltage at contact discharge	6 kV
Interference immunity to cable-borne interference	V
<ul> <li>Interference immunity on supply lines acc. to IEC 61000-4-4</li> </ul>	Yes
<ul> <li>Interference immunity on signal cables acc. to IEC 61000-4-4</li> </ul>	Yes
Interference immunity against voltage surge	
<ul> <li>Interference immunity on supply lines acc. to IEC 61000-4-5</li> </ul>	Yes
Interference immunity against conducted variable disturbance	ce induced by high-frequency fields
Interference immunity against high-frequency radiation acc. to IEC 61000-4-6	Yes
Emission of radio interference acc. to EN 55 011	
Limit class A, for use in industrial areas	Yes; Group 1
Limit class B, for use in residential areas	Yes; When appropriate measures are used to ensure compliance with the limits for Class B according to EN 55011
Degree and class of protection	
IP degree of protection	IP20
Standards, approvals, certificates	
CE mark	Yes
UL approval	Yes
cULus	Yes
FM approval	Yes
RCM (formerly C-TICK)	Yes
KC approval	Yes
Marine approval	Yes
Ambient conditions	
Free fall	
Fall height, max.	0.3 m; five times, in product package
Ambient temperature during operation	
● min.	-20 °C
• max.	60 °C; Number of simultaneously activated inputs or outputs 4 or 3 (no adjacent points) at 60 °C horizontal or 50 °C vertical, 8 or 6 at 55 °C horizontal or 45 °C vertical
<ul> <li>horizontal installation, min.</li> </ul>	-20 °C
<ul> <li>horizontal installation, max.</li> </ul>	60 °C
<ul> <li>vertical installation, min.</li> </ul>	-20 °C
vertical installation, max.	50 °C
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Air pressure acc. to IEC 60068-2-13	
Operation, min.	795 hPa
Operation, max.	1 080 hPa
Storage/transport, min.	660 hPa
	1 080 hPa
Storage/transport, max.  Altitude during expertise relating to see level.	I UOU IIFA
Altitude during operation relating to sea level	1 000 m
Installation altitude, min.	-1 000 m
Installation altitude, max.	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
Relative humidity	
Operation, max.	95 %; no condensation
Vibrations	
<ul> <li>Vibration resistance during operation acc. to IEC 60068-2-6</li> </ul>	2 g (m/s²) wall mounting, 1 g (m/s²) DIN rail
Operation, tested according to IEC 60068-2-6	Yes
Shock testing	
• tested according to IEC 60068-2-27	Yes; IEC 68, Part 2-27 half-sine: strength of the shock 15 g (peak value), duration 11 ms
Pollutant concentrations	
<ul> <li>SO2 at RH &lt; 60% without condensation</li> </ul>	S02: < 0.5 ppm; H2S: < 0.1 ppm; RH < 60% condensation-free
configuration / header	
configuration / programming / header	

Programming language	
— LAD	Yes
— FBD	Yes
SCL	Yes
Know-how protection	
<ul> <li>User program protection/password protection</li> </ul>	Yes
<ul> <li>Copy protection</li> </ul>	Yes
Block protection	Yes
Access protection	
<ul> <li>protection of confidential configuration data</li> </ul>	Yes
<ul> <li>Protection level: Write protection</li> </ul>	Yes
<ul> <li>Protection level: Read/write protection</li> </ul>	Yes
Protection level: Complete protection	Yes
programming / cycle time monitoring / header	
<ul><li>adjustable</li></ul>	Yes
Dimensions	
Width	90 mm
Height	100 mm
Depth	75 mm
Weights	
Weight, approx.	370 g

4/12/2021

last modified: